# **Agenda**



## **Technology partner Porsche Engineering**



## The Future. Since 1931.



Since 90 years, we have been developing the vehicle technology of tomorrow.

We are carrying on the **tradition** of **Ferdinand Porsche's design studio**.

Along with our customers, we are developing the **intelligent**, **connected vehicle** of the **future** — utilising wide **vehicle** and **digital expertise**.



## Porsche Engineering - An overview

### **MAIN FOCUS**

Digital vehicle technologies

Whole vehicle integration

### **LOCATIONS**

11 sites

In Germany, Italy, Czech Republic, Romania and China

#### **HERITAGE**



100% subsidiary of Dr. Ing. h.c. F. Porsche AG

### **EMPLOYEES**

1,500 employees

Around **60%** working on **digital technologies** and **e-mobility** 

**450 software specialists** in the group already



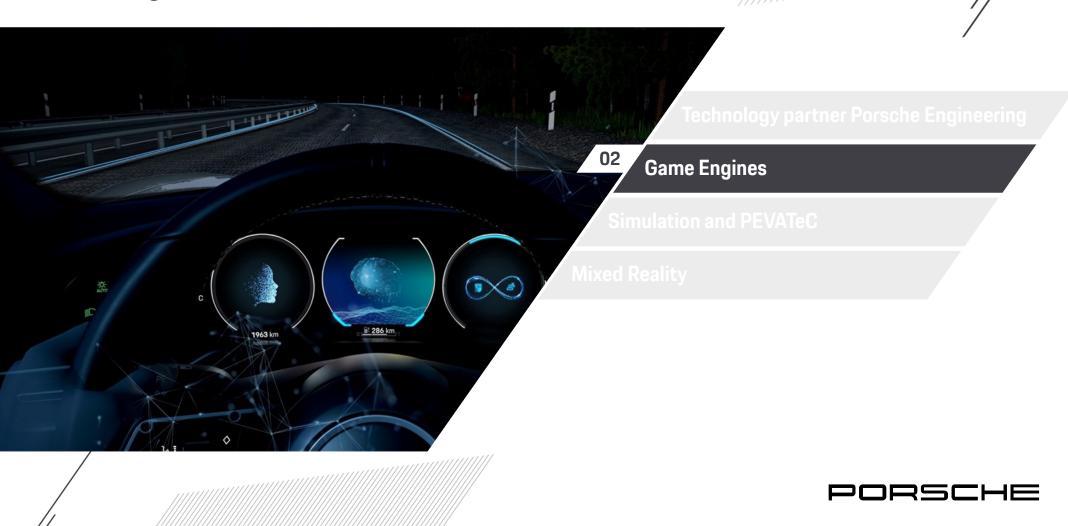


## Inno Network



The Porsche Engineering sites are integrated in an international network of competence centres with focus













## Game Engines – An overview

#### **Currently most used Game Engines:**

Game Engines as a **framework** for the creation of real-time 3D applications



"The most powerful real-time 3D creation platform"



"The leading platform for creating interactive, real-time content"

**Component parts** of Game Engines

Graphics engine

Physics engine

**Sound system** 

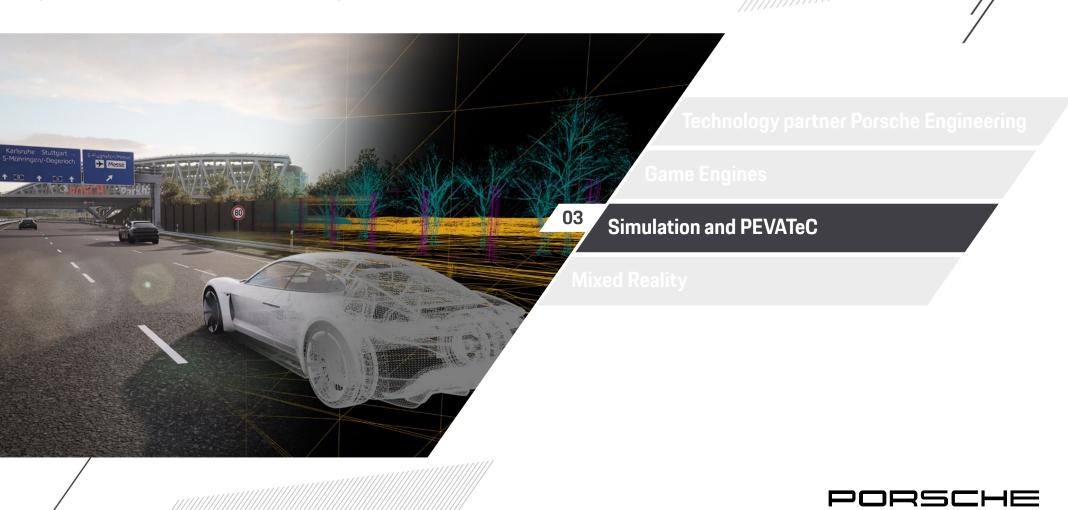
Storage management

Game Engines as a basic framework that is expanded upon with users' own implementations

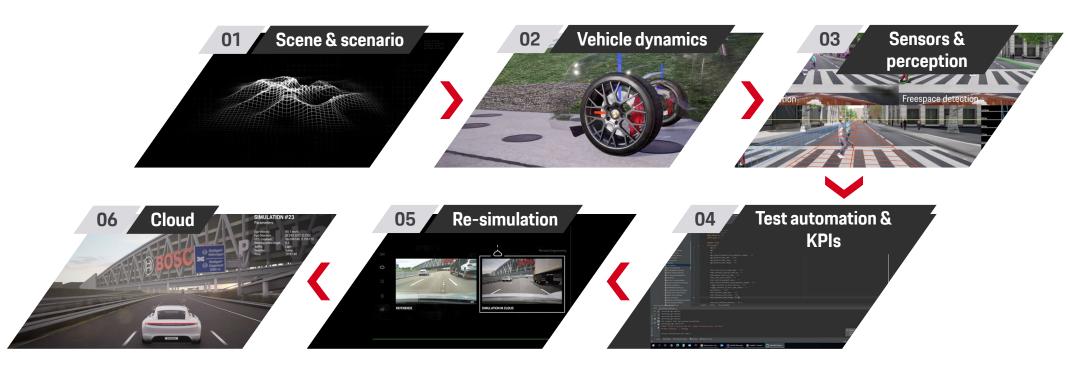




## **Simulation and PEVATeC**



# Game Engines meet automated driving: Virtual testing in the PEVATeC simulation environment

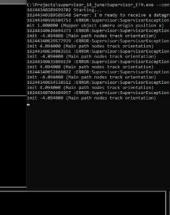




## **Example: ADAS/HAD in PEVATeC**

Closed loop virtual testing for automated driving functions
PEVATeC + advanced driver assistance system function + debugger/visualisation





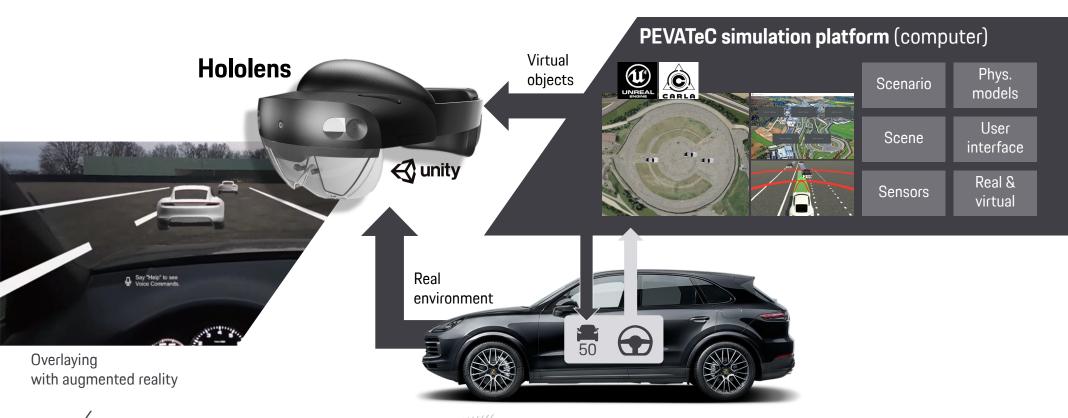


## **Mixed Reality**



PORSCHE

# Example: Mixed Reality – Testing of ADAS/HAD by PEVATeC





# Example: Mixed Reality – Testing of ADAS/HAD by PEVATeC

#### Simple running of the test

- Low-risk execution
   of critical and complex test manoeuvres
- High reproducibility
- Saving time and costs
- Portability between SiL/ HiL/ FiL
- Distributed systems and scenario-based testing



#### Integration into early-function development

- Independency from interface partners (sensors, control devices, etc.)
- Use of different sensors/ interchangeable in simulation
- Ability to compare different software/ algorithm versions
- Subjective perception of driving comfort by the driver

